Optimization problems in energy economics: On the impact of tax uncertainty on optimal investment into carbon abatement technology

Rüdiger Frey ruediger.frey@wu.ac.at joint work with Katia Colaneri, Tor Vergata and Verena Köck, WU

Vienna University of Economics and Business (WU)

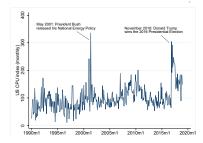
QFin@Work, Tor Vergata, April 2023

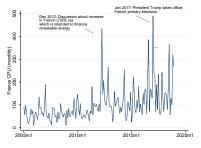
#### Introduction

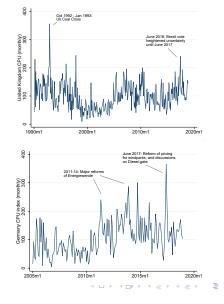
- According to many economists, carbon taxes and emissions trading (carbon price) are a key policy tool for fighting climate change (e.g. Nordhaus [1993], Golosov et al. [2014])
- Most of this work is concerned with optimal tax schemes for an efficient emission reduction (Nordhaus [1993], Golosov et al. [2014])
- In reality (environmental-) tax policy is affected by many uncertain factors such as political sentiment, outcome of elections, lobbying or international climate policy, so that future tax rates are random
- In fact Climate Policy Uncertainty and its impact on asset prices and investor decisions has become an active research topic and there are formal Climate Policy Uncertainty Indices

#### Introduction

# Climate Policy Uncertainty Index (Berestycki et al. (2022))







3 / 20

### Our contribution

- We study how uncertainty about future carbon tax rates affect investment strategy of a stylized electricity producer who can invest in emission abatement technology
- Investments are done continuously in time but are irreversible and subject to transaction cost ⇒ Producer is faced with a dynamic control problem.
- Mathematical contribution. Analysis of the ensuing control problem for jump diffusions (Characterization of value function, classical solutions etc.)
- Financial contribution (ongoing). Numerical experiments on the impact of various forms of tax- and price uncertainty and of the structure of production and abatement technology on investment into abatement technology.

#### Related work

- Fuss et al. [2008] Numerical analysis of the impact of policy uncertainty on investment in abatement technology in a real options model via discrete time dynamic programming; a related study by the International Energy Agency is Yang et al. [2008]
- Empirical studies on impact of carbon taxes include Aghion et al. [2016] and Martinsson et al. [2022].
- There is also an empirical literature on climate policy uncertainty and climate policy uncertainty indices

#### The model

- We consider a stylized monopolistic electricity producer, who has to decide on the amount  $q \ge 0$  to be produced at every t and on investments into abatement technology.
- The producer pays taxes on emissions represented by tax rate  $\tau$ .
- Instantaneous profit of the producer is given by the function

$$\Pi(q, I, \tau, y) = p(q, y)q - C(q, I, \tau, y) \tag{1}$$

Here p(q, y) is the inverse demand function and  $C(q, I, \tau, y)$  the cost function for producing q units of electricity, given current investment level I and tax rate  $\tau$  a

• At every *t* producer chooses *q* to maximise her instantaneous profit; optimal profit is

$$\Pi^*(I,\tau) = \max_{q \ge 0} \Pi(q,I,\tau).$$
<sup>(2)</sup>

• Often we consider the simpler case where *p* and *q* are fixed or where the factor process is not present.

## Investment in abatement technology

 Producer chooses rate γ = (γ<sub>t</sub>)<sub>t≥0</sub> at which she invests in abatement technology. For a given strategy γ, the investment *I* has dynamics

$$I_t = I_0 + \int_0^t \gamma_s \mathrm{d}s - \int_0^t \delta I_s \mathrm{d}s + \sigma W_t, \quad t \ge 0$$
(3)

where W is a Brownian motion, 0  $\leq \delta < 1$  the depreciation rate and  $\sigma \geq$  0 (typically small).

- We assume  $\gamma_t \ge 0$  for all t (irreversible investment); A denotes the set of admissible strategies.
- Investment is subject to build up- or transaction cost given by  $\kappa\gamma^2$  (penalization of rapid build up of a batement technology).
- Investment is financed by borrowing at interest rate r > 0

# Optimal investment problem

• Goal of the producer: choose strategy  $\gamma$  to maximize total profits up to time  $\mathcal{T}>$  0, that is

$$\max_{\gamma \in \mathcal{A}} \mathbb{E}_{t} \left[ \int_{t}^{T} \left( \Pi^{*}(I_{s}, \tau_{s}) - \gamma_{s} - \kappa \gamma_{s}^{2} \right) e^{-r(s-t)} \mathrm{d}s + e^{-r(T-t)} h(I_{T}) \right]$$
(4)

- $h(\cdot)$  accounts for the residual value of the abatement technology at time T.
- In the paper this problem is solved (numerically) via dynamic programming equation

#### Examples

## Production function: filter technology

- Let X be the input, say, coal with price  $\bar{c}$  per unit.
- Amount of emission (CO<sub>2</sub>) per unit of X is e<sub>0</sub>. Filters ⇒ emissions are reduced by e<sub>1</sub>(1).
- Total emission:  $e(X, I) = X(e_0 e_1(I))$ , where abatement function  $e_1(\cdot)$  is increasing, concave and bounded by  $e_0$
- Q(X) is electricity that can be produced from X units coal, for  $Q(\cdot)$  increasing and concave.
- This gives the following cost function for producing *q* units of electricity

$$C(q, I, \tau) = Q^{-1}(q)(\bar{c} + \tau(e_0 - e_1(I))),$$
(5)

### Example 2: Two technologies

- The energy producer has access to two production technologies, e.g. coal or gas and solar panels.
- Gas costs  $c_b(y)$  per unit and emits  $e_b$  tons of  $CO_2$  per unit.
- $Q_b(X)$  electricity produced with X units of gas.
- Green production has zero marginal cost, does not emit CO<sub>2</sub>.
- $c_g I$  electricity produced green for given investment I.
- Operating cost for green technology  $C_0(I)$

$$C(q, I, \tau) = \begin{cases} C_0(I) & \text{if } q - c_g I \le 0, \\ C_0(I) + (c_b(y) + e_b \tau) Q_b^{-1}(q - c_g I) & \text{if } q - c_g I > 0, \end{cases}$$
(6)

#### Examples

### Tax rate

In the numerical experiments we consider scenarios with 2 states (values of the tax process)  $\tau^1=0<\tau^2$ 

- Random tax increase. Here  $\tau_0 = 0$  but producer expects  $\tau$  to increase to  $\tau^2$  at random later state, eg. as government implements international climate treaties; probability of upward jump in (t, t + h] is approx.  $g_{12}h$
- Tax reversal. Here τ is initially in the high-tax state τ<sup>2</sup>, but energy producer expects a correction (jump to 0 at a later date) perhaps due to political lobbying or a change in government ("Trump after Biden"); probability of downward jump in (t, t + h] is approx. g<sub>21</sub>h

#### The tax scenarios

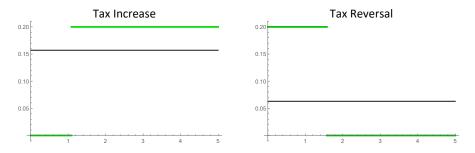


Figure: Tax policies. **black** deterministic tax rate, **green** random tax rate. In each panel the quantity  $\mathbb{E}\left[\int_{0}^{T} \tau_{s} ds\right]$  is identical for random and deterministic tax

#### The value function

- The value function is the optimal value (profit, utility etc) one can achieve if one starts at a given time and state.
- In our case

$$V(t, I, \tau) = \max_{\gamma \in \mathcal{A}} \mathbb{E} \Big[ \int_{t}^{T} \left( \Pi^{*}(I_{s}, \tau_{s}) - \gamma_{s} - \kappa \gamma_{s}^{2} \right) e^{-r(s-t)} \mathrm{d}s \qquad (7)$$
$$+ e^{-r(T-t)} h(I_{T}) \mid I_{t} = I, \tau_{t} = \tau \Big] \qquad (8)$$

- In stochastic control one (tries to) characterize V by a partial differential equation, the HJB equation;
- Solving this PDE (usually numerically) gives information on the optimal value and the optimal strategy
- Famous example in finance: Merton portfolio problem of maximizing expected utility of a trading portfolio

### The HJB equation

In our case the HJB equation is

$$v_t(t, I, \tau^0) + \Pi^*(I, \tau^1) - rv(t, I, \tau) + [v(t, I, \tau^2) - v(t, I, \tau^1)]g_{12}(t)$$
(9)

$$+\frac{\sigma^2}{2}v_{II}(t,I,\tau)+\sup_{0\leq\gamma}v_I(t,I,\tau)(\gamma-\delta I)-(\gamma+\kappa\gamma^2)=0$$
(10)

with the terminal condition  $v(T, I, \tau) = h(I)$ . Looks nice ...

Optimal strategy. The optimal investment rate is

$$\gamma^*(t, I, au, y) = (V_I(t, I, au) - 1)^+/2\kappa$$

(Trade-off between expected future profits and current cost.)

### Numerical experiments: Setup and overview

- Throughout we consider the case where q is equal to  $\bar{q} = 10$ ,  $\delta = 0.1, \sigma = 0.05, T = 10$ .
- Filter technology. Cost function is increasing and concave in I, residual value h(I) = 0;
- Two technologies: residual value  $h(I) \approx I$ .
- Tax rate: 2 states  $\tau^1 = 0$ ,  $\tau^2 > 0$ , transition intensity  $g_{12} = 0.25, g_{21} = 0$  (random tax increase) resp.  $g_{21} = g_{12} = 0.25$

We show results on

- Optimal investment rate for different buildup cost  $\kappa$
- Comparison of average investment and emission reduction to a deterministic scenario with same average tax rate for tax reversal and random tax increase scenario

## Optimal investment for tax increase scenario (filter)

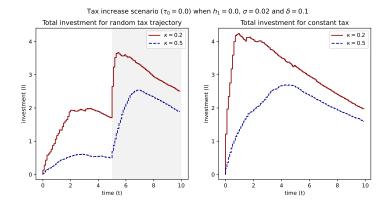


Figure: Optimal investment  $I^*(t)$  for tax increase; left: random tax, right: constant tax. Note that there is a substantial amount of investment already before the jump in  $\tau$  (hedging)

## Optimal investment for tax reversal scenario (filter)

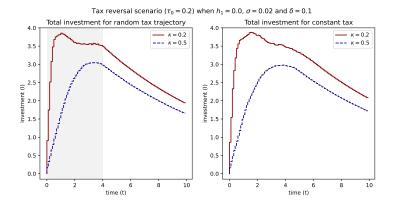


Figure: Optimal investment  $I^*(t)$  for tax reversal; left: random tax, right: constant tax.

Parameter:  $h_1 = 1.0$ ,  $p_a = 0.3$ ,  $\kappa = 0.5$ ,  $\sigma = 0.05$  and  $\delta = 0.05$ 

## Optimal investment for both scenarios (2 technologies).

14 14 12 12 10 10 nvestment (I) investment (I) 8 8 6 6. 4 4 2 2 random tax andom tax 0 constant tax constant tax Ó 10 10 time (t) time (t)

Figure: Optimal investment  $I^*(t)$  for 2 technologies; left: tax increase, right: tax reversal The impact of taxes on  $\gamma$  resp. I is usually smaller than in filter case

Parameter:  $h_1 = 1.0$ ,  $p_a = 0.3$ ,  $\kappa = 0.5$ ,  $\sigma = 0.05$  and  $\delta = 0.05$ 

## Average emissions (filter)

$\kappa$	random	constant	$\kappa$	random	constant
0.2	5.45	3.75	0.2	4.25	3.83
0.5	8.90	6.76	0.5	7.20	6.07

Table: left: random tax increase; right: tax reversal. The constant tax leads on average to lower emissions in both cases.

For the two technology case there is no clear ordering of the different tax policies.

## Summary and Conclusion

- For the filter technology random tax seems to be worse than deterministic benchmark;
- For 2 technologies on clearcut comparison possible; (investment mainly driven by low marginal cost of producing green)
- Results for the case with divisible investment (stochastic control) complement the real options approach of Fuss et al. [2008]. In particular, we see that investment buildup cost matter a lot.
- Further work (short term)
  - Study case with endogenous price and quantity
  - Exogenous noise in prices/demand function, possibly correlated with switching intensity
- Further work (longer term)
  - Cost of capital: higher interest rate for borrowing than for investing
  - Study case where investor learns switching intensity (filtering)
  - Equilibrium considerations (many small producers ⇒ mean-field game)

- P. Aghion, A. Dechezleprêtre, D. Hémous, R. Martin, and J. Van Reenen. Carbon taxes, path dependency, and directed technical change: Evidence from the auto industry. *Journal of Political Economy*, 124(1): 1–51, 2016. doi: 10.1086/684581.
- Christian Beck, Sebastian Becker, Patrick Cheridito, Arnulf Jentzen, and Ariel Neufeld. Deep splitting method for parabolic PDEs. *SIAM Journal on Scientific Computing*, 43(5):A3135–A3154, 2021.
- Rüdiger Frey and Verena Köck. Deep neural network algorithms for parabolic pides and applications in insurance and finance. *Computation*, 10, 2022. https://doi.org/10.3390/computation10110201.
- S. Fuss, J. Szolgayova, and M. Obersteiner. Investment under market and climate policy uncertainty. *Applied Energy*, 85:708–721, 2008.
- Maximilien Germain, Huyen Pham, and Xavier Warin. Approximation error analysis of some deep backward schemes for nonlinear pdes. *SIAM Journal of Scientific Computing*, 22:A28 –A56, 2022.
- M. Golosov, J. Hassler, P. Krusell, and A. Tsyvinski. Optimal taxes on fossil fuel in general equilibrium. *Econometrica*, 82(1):41–88, 2014.

- O. A. Ladyzenskaja, V. A. Solonnikov, and N. N. Ural'ceva. *Linear and Quasilinear Equations of Parabolic Type*. American Mathematical Society, Providence, Rhode Island, 1968.
- G. Martinsson, P. Stromberg, L. aszlo Sajtos, and C. Thomann. Carbon pricing and firm-level CO2 abatement: Evidence from a quarter of a century-long panel. working paper, European Corporate Governance Institute, 2022. Available at SSRN: https://ssrn.com/abstract=4206508 or http://dx.doi.org/10.2139/ssrn.4206508.
- W. Nordhaus. Optimal greenhouse-gas reduction and tax policy in the 'DICE' model. *The American Economic Review*, 82:313–317, 1993.
- Huyên Pham. Optimal stopping of controlled jump diffusion processes: a viscosity solution approach. *Journal of Mathematical Systems, Estimation and Control*, 8:1–27, 1998.
- M. Yang, W. Blyth, and R. Bradley. Climate policy uncertainty and investment risk. Technical report, International Energy Association, Paris, 2008.